

***Solutions to the Exam Digital Communications I  
given on the 11th of June 2007***

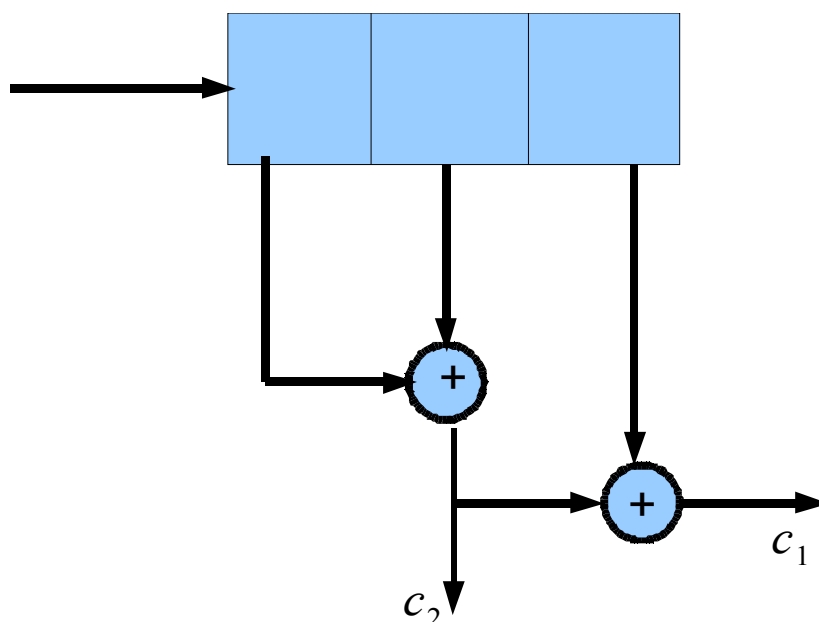
**Question 1 (14p)**

a) (2p) If X and Y are independent Gaussian variables, then  $E[XY]=0$  always.  
(Answer with TRUE or FALSE)

ANSWER: False. (Only if  $E(X)=0$  or  $E(Y)=0$ .)

b) (3p) Consider a rate 1/2 convolutional code with generator sequences  $g_1=(111)$  and  $g_2=(110)$ . Assume that BPSK modulation is used to transmit the coded bits. Draw a shift register for the encoder.

ANSWER:



c) (2p) One advantage of non-coherent demodulation over coherent demodulation, is that the demodulator does not need to implement phase estimation.

(Answer with TRUE or FALSE)

ANSWER: True.

d) (3p) A receiver that implements the ML decision rule is always optimal in the sense of minimum symbol error probability.

(Answer with TRUE or FALSE)

ANSWER: False.

e) (2p) The MAP decision rule is a special case of the ML rule.

(Answer with TRUE or FALSE)

ANSWER: False. ML is a special case of MAP.

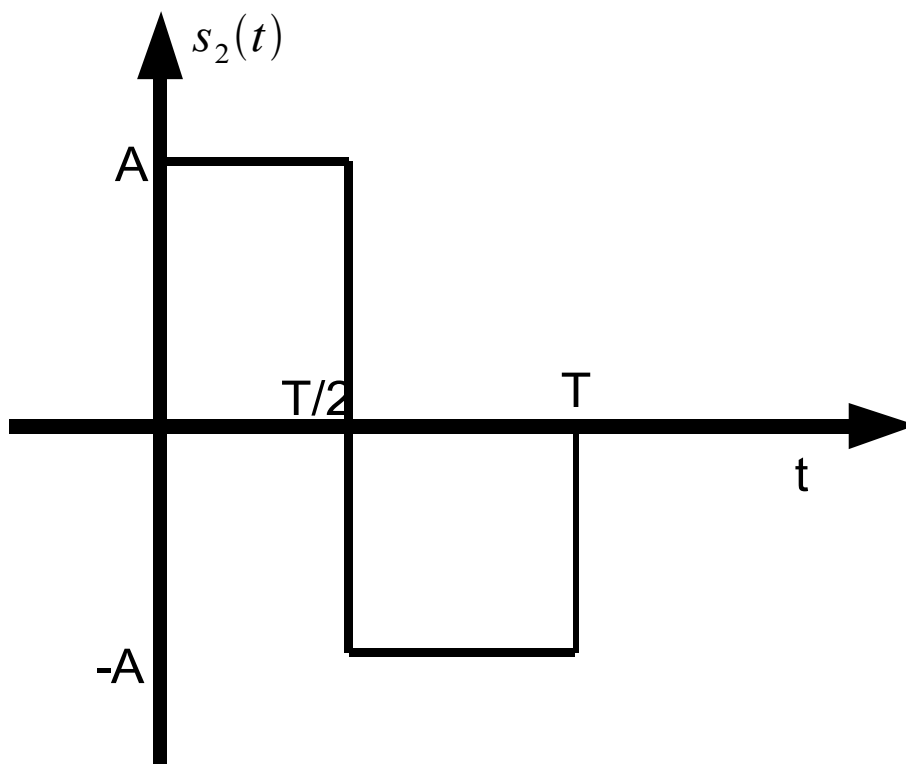
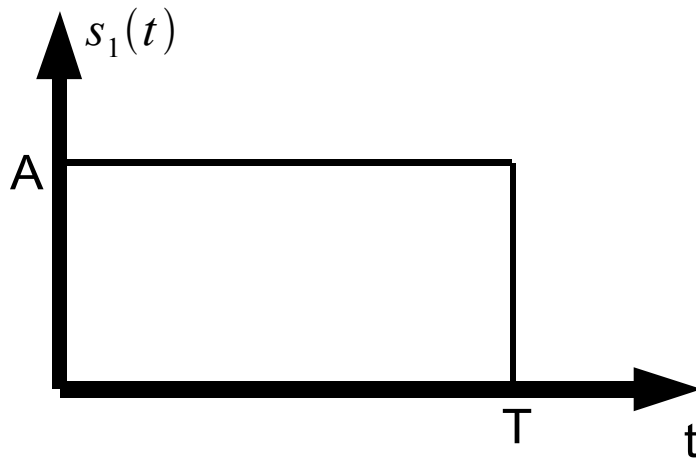
f) (2p) PSK is a special case of QAM.

(Answer with TRUE or FALSE)

ANSWER: True.

**Question 2 (12p)**

Here we study a binary system with signal two alternatives:  $s_1(t)$  and  $s_2(t)$ . The bits are assumed to be statistically independent and of equal probability. The system is an AWGN channel with noise power spectral density given by  $N_0/2$ .



a) Please express  $E_b$  (the average energy per bit) as a function of  $A$  and  $T$ . (2p)

**Solution:** The energy for  $s_1(t)$  is  $E_1 = \int_0^T s_1^2(t) dt = A^2 T$  and the energy for  $s_2(t)$  is  $E_2 = \int_0^T s_2^2(t) dt = A^2 T$ . Hence, the average energy per bit is  $E_b = A^2 T$ .

b) Find a basis for the signal space and draw the signal constellation that is the vectors corresponding corresponding to  $s_1(t)$  and  $s_2(t)$ . Please label the axis in terms of  $E_b$ . (4p)

**Solution:** One possible basis is  $\{\Psi_1(t), \Psi_2(t)\}$  where  $\Psi_i(t) = s_i(t) / \sqrt{E_b}$ . Hence, the signal constellation is:  $s_1(t) = [\sqrt{E_b}, 0]^T$  and  $s_2(t) = [0, \sqrt{E_b}]^T$

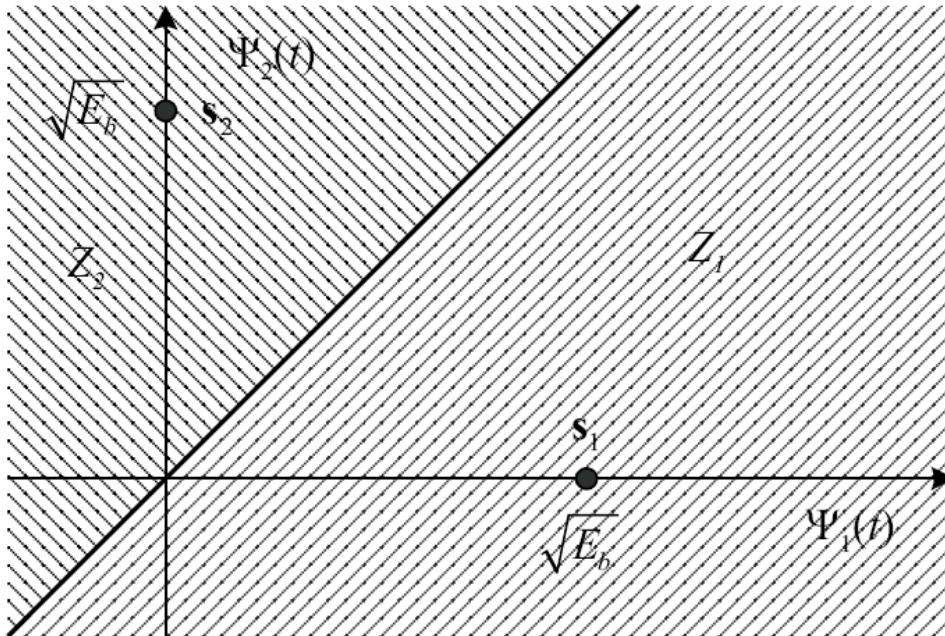
c) What is the smallest value of  $E_b/N_0$  in dB required to reach a bit error probability of  $10^{-3}$  if we assume that we are using the optimum receiver (which minimizes the bit error probability)? (4p)

**Solution:** The maximum likelihood receiver will minimize the bit error probability since all signal

alternatives are equally likely. The distance between the signal alternatives is  $d = \sqrt{2E_b}$  and the bit error probability is  $P_b = Q\left(\sqrt{d^2/2N_0}\right) = Q\left(\sqrt{E_b/N_0}\right) = 10^{-3}$ . The required  $E_b/N_0$  in dB is approximately 9.80dB.

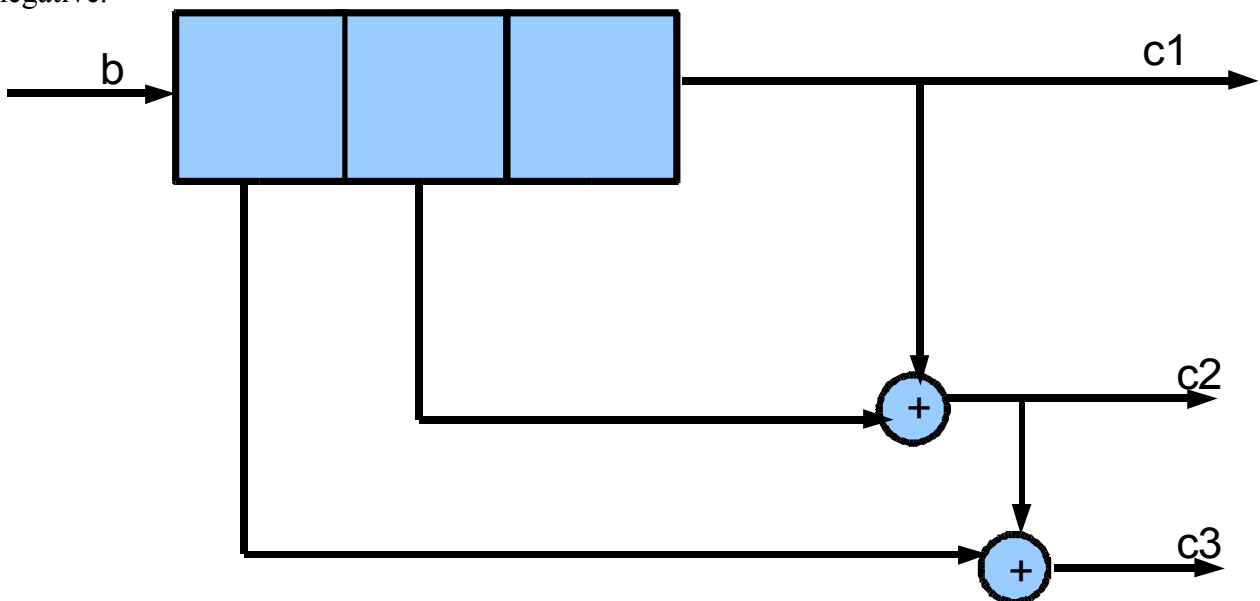
**d)** Please draw the decision regions for the receiver in part c). (2p)

**Solution:** The ML receiver is a minimum-distance receiver and the decision regions  $Z_1$  and  $Z_2$  are depicted below.

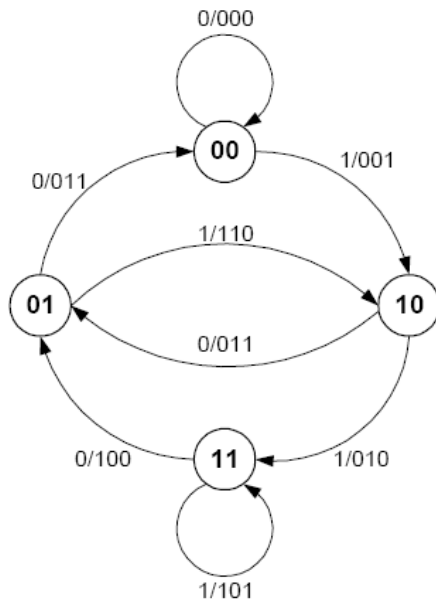


**Question 3** (12p)

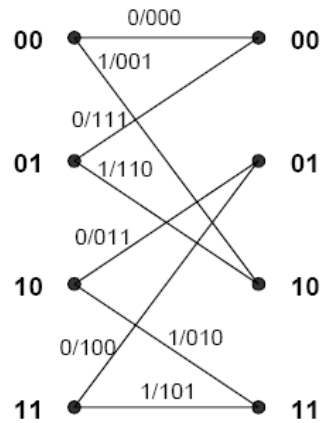
In this problem, we will consider a convolutional encoder. It is given in the figure below. The information bit  $b$  gives rise to three coded bits  $c_1, c_2$  and  $c_3$ , which are transmitted over an AWGN channel using binary PAM with root-raised cosine pulses with roll-off factor  $\alpha = 0.2$ . The PAM pulses are transmitted at a rate of 1000 pulses/second. If the coded bit is 1, then the transmitted amplitude is positive. Conversely, if the coded bit is 0, then the transmitted amplitude is negative.



**a)** Draw the state diagram and a trellis section of the encoder. Please make sure to label the transitions. (4p)



State diagram



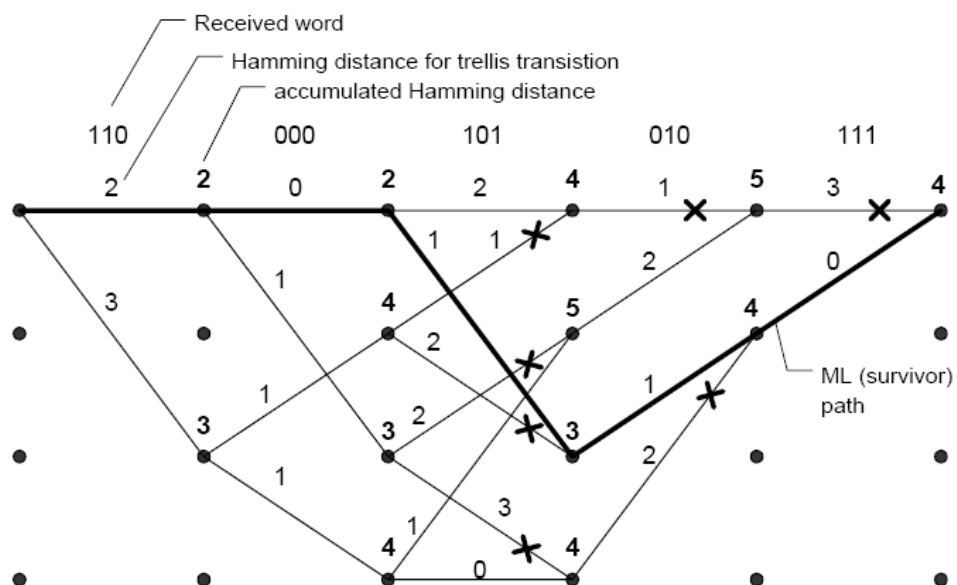
Trellis section

**Solution:** The state diagram and trellis are shown in the figure below.

c) Now suppose the sampled output of the receiver matched filter is  $\{1.51, 0.63, -0.04, -1.14, -0.56, -0.57, 0.07, -1.53, 0.9, -1.68, 0.9, -0.98, 1.99, 0.04, 0.76\}$

This sequence corresponds to the transmitted sequence  $c_1, c_2, c_3, c_1, c_2, c_3, \dots$  which is generated from a packet of *three* information bits. The encoder is assumed to be in the all-zero state at the beginning and ending of the transmission. The encoder is forced into the ending state by appending two zero bits to the information bit sequence. Use *hard decision* decoding to estimate the transmitted information bits. (8p)

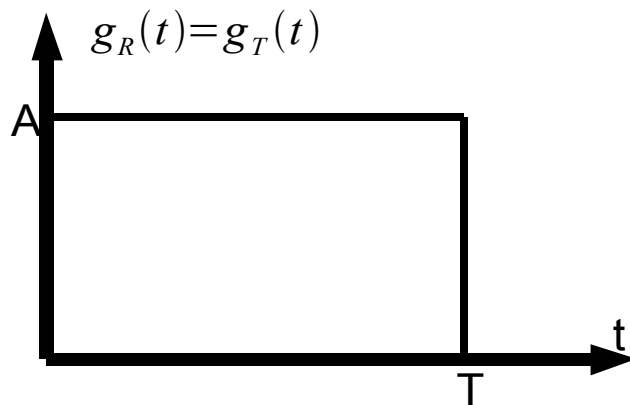
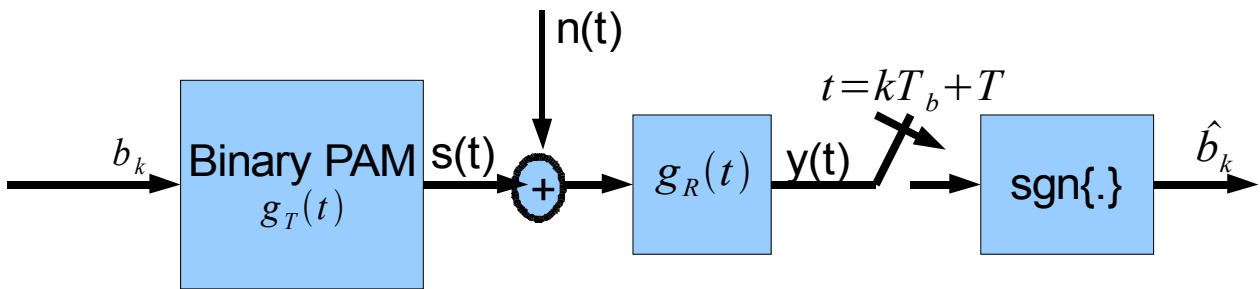
**Solution:** The hard decoded channel bits are  $\{1, 1, 0, 0, 0, 0, 1, 0, 1, 0, 1, 0, 1, 1, 1\}$ . The trellis with the decoded path (the path at minimum Hamming distance from the received channel bits) is show below.



We see that the decoded information bits are  $\{0, 0, 1\}$ .

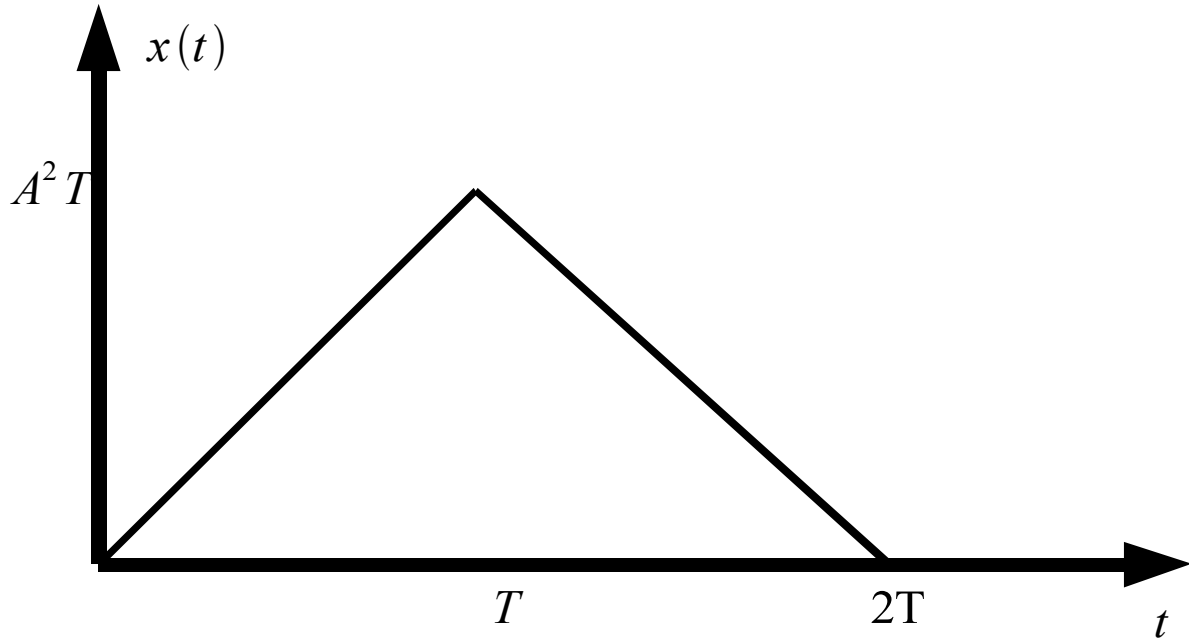
**Question 4** (12p)

In this problem, we are considering a binary PAM system. The pulse shape is given by  $g_T(t)$  and the data rate is  $R_b=1/T_b$ . We can thus conclude that the time between consecutive pulses equals  $T_b$  seconds. Furthermore,  $s(t)=\sum_{k=-\infty}^{\infty} b_k g_T(t-kT_b)$ , where  $b_k \in \{-1, +1\}$  is the  $k$ th transmitted bit. The system is depicted in the block diagram below. Here,  $\text{sgn}\{q\}$  denotes the sign of  $q$ , that is if  $q$  is positive then  $\text{sgn}\{q\}=+1$  and if  $q$  is negative then  $\text{sgn}\{q\}=-1$ . Furthermore, the sampling of the  $k$ th bit is performed at time  $t=kT_b+T$  as indicated in the figure. The channel is an AWGN channel. The additive noise is denoted  $n(t)$  and has noise power spectral density  $N_0/2$ . The decision on the  $k$ th bit is given by the sign of  $y(kT_b+T)$ , where  $y(t)$  is the output from the matched filter (which has impulse response  $g_R(t)$ ). The target bit error rate is  $P_b=10^{-4}$ , and the energy per bit is denoted by  $E_b$ .



a) What is the maximum possible data rate if the transmission must be ISI-free? Answer with an expression in  $T$ . (6p)

**Solution:** It follows from the block diagram that  $y(t)=\sum_{l=-\infty}^{\infty} b_l x(t-lT_b)+v(t)$  where  $x(t)=g_T(t)*g_R(t)$  and  $v(t)=n(t)*g_R(t)$ , and the sampled output from the matched filter is  $y(kT_b+T)=\sum_{l=-\infty}^{\infty} b_l x(T+kT_b-lT_b)+v(kT_b+T)=b_k x(T)+\sum_{-\infty, l \neq k}^{\infty} b_l x(T+(k-l)T_b)+v(kT_b+T)$ . There will be no ISI if  $x(T+nT_b)=0$  for all nonzero  $n$ . From the figure, it is obvious that this is equivalent to  $T+nT_b \geq 2T \Rightarrow T_b \geq T$ . Hence, the maximum data rate for ISI free transmission is  $R_b=1/T$ .



b) What is the required  $E_b/N_0$  in dB for the ISI-free system to meet the bit error target? (6p)

**Solution:** The  $k$ th noise sample is  $v(kT_b+T)=n(t)*g_R(t)_{t=kT_b}$ . The noise sample will be a zero-mean Gaussian random variable with variance  $E_g N_0/2$ , where  $E_g$  is the energy of  $g_R(t)$ .

$E_g = \int_{-\infty}^{\infty} g_R^2(t) dt = A^2 T$ . Clearly,  $E_g$  is also the energy of  $g_T(t)$  and since  $b_k = \pm 1$ , we have that  $E_b = E_g$ . Conditioned on that  $b_k = -1$ , a bit error occurs with probability

$$Pr\{y(T+kT_b) > 0 \mid b_k = -1\} = Pr\{-A^2 T + n(kT_b) > 0\} = Pr\{-E_b + n(kT_b) > 0\}$$

$$Pr\{n(kT_b)/\sqrt{E_b N_0/2} > \sqrt{2 E_b/N_0}\} = Q(\sqrt{2 E_b/N_0})$$

Due to symmetry,  $P_b = (P_b \mid b_k = -1) = (P_b \mid b_k = +1)$  and  $E_b/N_0 = \dots = 8.39 \text{ dB}$ .