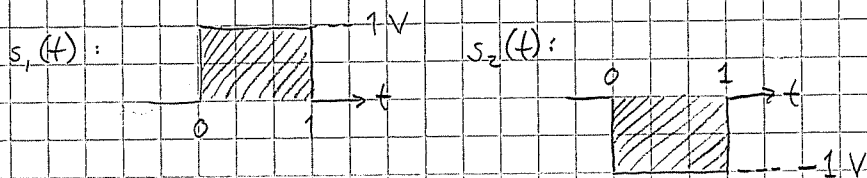


# Tut 3, Ex 1



Here,  $E_s = \int_0^T |s_1(t)|^2 dt = \int_0^T |s_2(t)|^2 dt = 1$

The signal is correlated on the receiving side. We obviously need only one correlator since the signals are antipodal.

It's convenient to normalise the/all correlator(s). Then the magnitude of a received symbol in the signal space will always be  $\sqrt{E_s}$  plus noise and we don't have to worry about scaling.

Correlator:  $f_1(t) = \frac{1}{\sqrt{E_s}} s_1(t) = s_1(t)$

Correlation metric:  $z = \int_0^T r(t) s(t) dt = \pm \sqrt{E_s} + n$

We want to make a decision such that  $p(s_1|z) \underset{s_2}{\overset{s_1}{\gtrless}} p(s_2|z)$ .

Which decision boundary does this give us?

$$p(s_1|z) \underset{s_2}{\overset{s_1}{\gtrless}} p(s_2|z) \Rightarrow \frac{p(z|s_1)p(s_1)}{p(z)} \underset{s_2}{\overset{s_1}{\gtrless}} \frac{p(z|s_2)p(s_2)}{p(z)}$$

$$\Rightarrow \frac{p(z|s_1)}{p(z|s_2)} \underset{s_2}{\overset{s_1}{\gtrless}} \frac{p(s_2)}{p(s_1)} \Rightarrow \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(z-\sqrt{E_s})^2}{2\sigma^2}\right) \underset{s_2}{\overset{s_1}{\gtrless}} \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{(z+\sqrt{E_s})^2}{2\sigma^2}\right) \underset{s_2}{\overset{s_1}{\gtrless}} \frac{p(s_2)}{p(s_1)}$$

$$\Rightarrow \frac{-(z-\sqrt{E_s})^2 + (z+\sqrt{E_s})^2}{2\sigma^2} \underset{s_2}{\overset{s_1}{\gtrless}} \ln \frac{p(s_2)}{p(s_1)} \Rightarrow z \underset{s_2}{\overset{s_1}{\gtrless}} \sqrt{E_s} \underset{s_2}{\overset{s_1}{\gtrless}} \sigma^2 \ln \frac{p(s_2)}{p(s_1)}$$

$$\Rightarrow z \underset{s_2}{\overset{s_1}{\gtrless}} \underbrace{\frac{\sigma^2}{2\sqrt{E_s}} \ln \frac{p(s_2)}{p(s_1)}}_{\gamma_0} \quad \text{and } \frac{\sigma^2}{\sqrt{E_s}} = 0.1. \text{ Note that } p(s_2) = 1 - p(s_1)$$

decision boundary

1.  $\gamma_0 = 0$
2.  $\gamma_0 = -0.0424$
3.  $\gamma_0 = 0.0693$

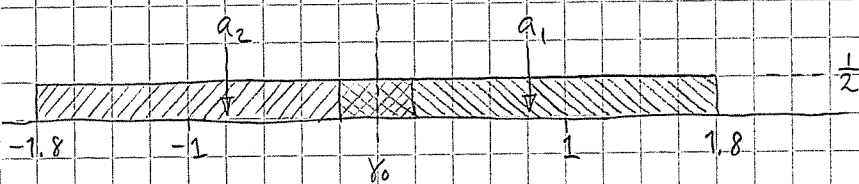
4. Increasing  $p(s_1) \Rightarrow \gamma_0$  becomes more and more negative and vice versa

### Tut 3. Ex 2

Now we want to examine the bit error probability, which since we only have two symbols is the same as the symbol error probability. For simplicity, we here pretend that the noise is uniformly distributed.

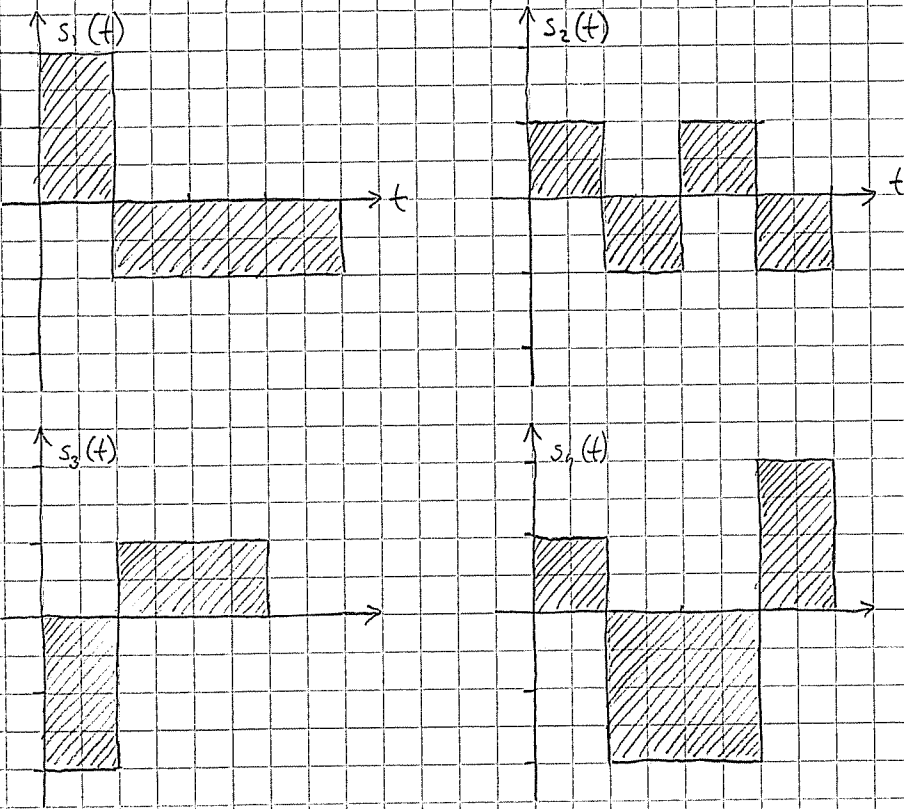
Correlation metric:  $z = \pm 0.8 + n_0$

$$p(s_1) = p(s_2) = 0.5 \Rightarrow \gamma_0 = 0 \quad (\text{see Ex 1})$$



$$P_B = P_S = 0.5 \cdot \int_0^{0.2} 0.5 d\epsilon + 0.5 \int_{-0.2}^0 0.5 d\epsilon = 0.1$$

Tut 3, Ex 3.



1. An obvious choice of basis is  $f_1(t)$ : [positive pulse at [0,1]]  $f_2(t)$ : [positive pulse at [1,2]]  
 $f_3(t)$ : [negative pulse at [0,1]]  $f_4(t)$ : [negative pulse at [1,2]]

Then  $\begin{bmatrix} s_1(t) \\ s_2(t) \\ s_3(t) \\ s_4(t) \end{bmatrix} = \underbrace{\begin{bmatrix} 2 & -1 & -1 & -1 \\ 1 & -1 & 1 & -1 \\ -2 & 1 & 1 & 0 \\ 1 & -2 & -2 & 2 \end{bmatrix}}_A \begin{bmatrix} f_1(t) \\ f_2(t) \\ f_3(t) \\ f_4(t) \end{bmatrix}$  The dimensionality of our signal space is then the rank of A.

$$\begin{bmatrix} 2 & -1 & -1 & -1 \\ 1 & -1 & 1 & -1 \\ -2 & 1 & 1 & 0 \\ 1 & -2 & -2 & 2 \end{bmatrix} \begin{matrix} \leftarrow \\ \\ \textcircled{1} \\ \end{matrix} \sim \begin{bmatrix} 0 & 0 & 0 & -1 \\ 1 & -1 & 1 & -1 \\ -2 & 1 & 1 & 0 \\ 1 & -2 & -2 & 2 \end{bmatrix} \begin{matrix} \\ \leftarrow \\ \\ \textcircled{1} \end{matrix} \sim \begin{bmatrix} 0 & 0 & 0 & -1 \\ 0 & 1 & 3 & -3 \\ -2 & 1 & 1 & 0 \\ 1 & -2 & -2 & 2 \end{bmatrix} \begin{matrix} \\ \\ \leftarrow \\ \textcircled{2} \end{matrix} \sim \begin{bmatrix} 0 & 0 & 0 & -1 \\ 0 & 1 & 3 & -3 \\ 0 & -3 & -3 & 4 \\ 1 & -2 & -2 & 2 \end{bmatrix} \begin{matrix} \\ \\ \leftarrow \textcircled{3} \\ \end{matrix} \sim \begin{bmatrix} 0 & 0 & 0 & -1 \\ 0 & 1 & 3 & -3 \\ 0 & 0 & 6 & -5 \\ 1 & -2 & -2 & 2 \end{bmatrix}$$

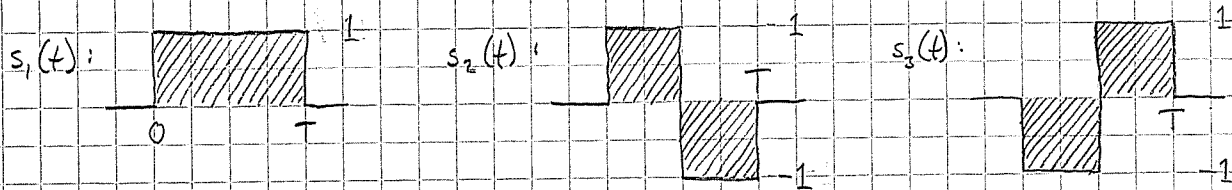
Rearrange:  $\begin{bmatrix} 1 & -2 & -2 & 2 \\ 0 & 1 & 3 & -3 \\ 0 & 0 & 6 & -5 \\ 0 & 0 & 0 & -1 \end{bmatrix}$  Full rank!  $\Rightarrow$  Dimensionality is 4.

2. Already done!

3. Signal distance:  $d_{m,n} = \sqrt{\int_0^1 |s_m(t) - s_n(t)|^2 dt}$ . But the  $\{f(t)\}$  is an ON-base so  $\int_0^1 f_m(t) f_n(t) dt = \begin{cases} 1 & m=n \\ 0 & m \neq n \end{cases}$ . Therefore we just have to look at the distances between the vectors, e.g.  $d_{1,2} = \sqrt{(2-1)^2 + (-1+1)^2 + (-1-1)^2 + (-1+1)^2} = \sqrt{5}$

Searching through all combinations we find that in fact  $d_{1,2}$  is the min. distance.

Tut 3. Ex 4.

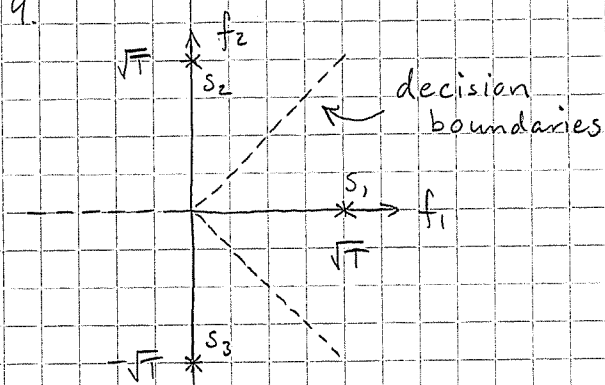


1. The dimensionality is clearly 2.
2. It's easy to see that  $s_1(t)$  is orthogonal to  $s_2(t)$  and  $s_3(t)$ , so we could choose e.g.  $s_1(t)$  and  $s_2(t)$  as basis vectors. In general we should however normalise the basis vectors (although it isn't necessary here since all signals have the same power) so we let

$$f_1(t) = \frac{1}{\sqrt{T}} s_1(t) \quad f_2(t) = \frac{1}{\sqrt{T}} s_2(t).$$

$$\Rightarrow \begin{bmatrix} s_1(t) \\ s_2(t) \\ s_3(t) \end{bmatrix} = \begin{bmatrix} \sqrt{T} & 0 \\ 0 & \sqrt{T} \\ 0 & -\sqrt{T} \end{bmatrix} \begin{bmatrix} f_1(t) \\ f_2(t) \end{bmatrix} \quad (\text{Note that the rank of the matrix is 2})$$

3, 4.



Since the signals are equiprobable, the decision boundaries fall exactly in the middle between the signals.

5.

$p(\text{error} | s_i)$  is the integral over the region outside the decision region, so the largest  $p(\text{error} | s_i)$  belongs to the  $s_i$  which has the smallest decision region  $\Rightarrow s_1(t)$  is the most sensitive to errors.

### Tut 3, Ex 4 Appendix

A derivation of the decision boundaries:

The received signal, corrupted by noise, is passed through the two correlators  $f_1(t)$  and  $f_2(t)$ . This gives us a point  $\mathbf{z}$  in the 2D signal space.

We then want to find the  $s_i$  that maximises  $p(\mathbf{z}|s_i)$ \*

$$p(\mathbf{z}|s_i) = \frac{1}{(\pi N_0)^{N/2}} \exp\left\{-\sum_{k=1}^N \frac{(z_k - s_{i,k})^2}{N_0}\right\} \quad i = 1, 2, \dots, M$$

N = dimensionality = 2  
M = #symbols = 3

$$= \frac{1}{\pi N_0} \exp\left\{-\frac{(z_1 - s_{i,1})^2 + (z_2 - s_{i,2})^2}{N_0}\right\} \quad \text{is what we want to maximise}$$

$$\Rightarrow \text{maximise } \log p(\mathbf{z}|s_i) = -\log(\pi N_0) - \frac{(z_1 - s_{i,1})^2 + (z_2 - s_{i,2})^2}{N_0}$$

$$\Rightarrow \text{minimise } (z_1^2 + s_{i,1}^2 - 2z_1 s_{i,1}) + (z_2^2 + s_{i,2}^2 - 2z_2 s_{i,2})$$

But  $s_{1,1} = \sqrt{T}$ ,  $s_{1,2} = 0$     $s_{2,1} = 0$     $s_{2,2} = \sqrt{T}$     $s_{3,1} = 0$     $s_{3,2} = -\sqrt{T}$

so  $z_1^2 + z_2^2$  and  $s_{i,1}^2 + s_{i,2}^2$  are equal for all  $i$ .

$$\Rightarrow \text{We want to maximise } z_1 s_{i,1} + z_2 s_{i,2}$$

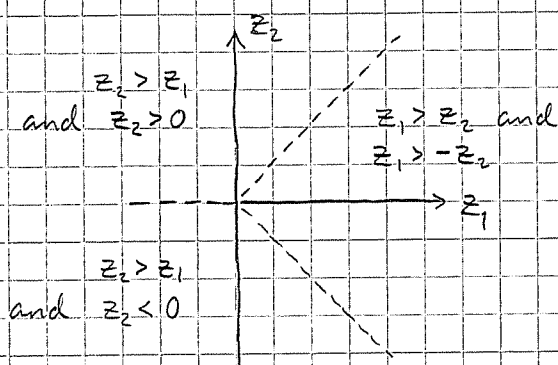
That is, choose

$$s_1 \quad \text{when} \quad z_1 \sqrt{T} > z_2 \sqrt{T} \quad \text{and} \quad z_1 \sqrt{T} > z_2 (-\sqrt{T})$$

$$s_2 \quad \text{when} \quad z_2 \sqrt{T} > z_1 \sqrt{T} \quad \text{and} \quad z_2 \sqrt{T} > z_2 (-\sqrt{T})$$

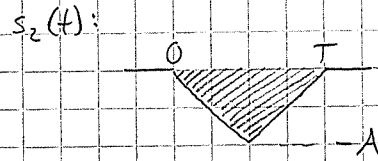
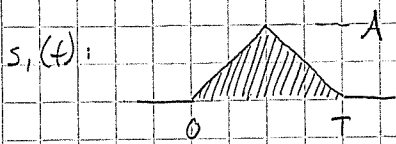
$$s_3 \quad \text{when} \quad z_2 (-\sqrt{T}) > z_1 \sqrt{T} \quad \text{and} \quad z_2 (-\sqrt{T}) > z_2 \sqrt{T}$$

This gives the decision regions:



\* Actually, we want to find the  $s_i$  that maximises  $p(s_i|\mathbf{z})$ , but  $p(s_i|\mathbf{z}) = p(s_i) \frac{P(\mathbf{z}|s_i)}{P(\mathbf{z})}$  and all  $s_i$  are equiprobable.

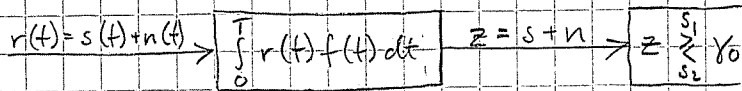
Tut 3, Ex 5.



$$E_s = E_b = 2 \int_0^T \left| \frac{2A}{T} t \right|^2 dt = \frac{8A^2}{T^2} \left[ \frac{1}{3} t^3 \right]_0^T = \frac{1}{3} A^2 T$$

⇒ Correlator :  $f_1(t) = \frac{1}{\sqrt{E_b}} s_1(t)$

Optimal receiver (in AWGN):



But what is the decision boundary  $\gamma_0$ ?

As usual we want to find the  $s_i$  that maximises  $p(s_i | z)$

⇒ maximise  $p(z | s_i) p(s_i)$

Since we normalised the correlator,  $s_i = \pm \sqrt{E_b}$ . If  $\text{var}(n(t)) = N_0/2$

then (again, with a normalised correlator)  $\text{var}(n) = N_0/2$ .

$$\left[ E \int_0^T n(t_1) f(t_1) dt_1 \int_0^T n(t_2) f(t_2) dt_2 = E \int_0^T \int_0^T n(t_1) n(t_2) f(t_1) f(t_2) dt_1 dt_2 = \frac{N_0}{2} \int_0^T |f(t)|^2 dt = \frac{N_0}{2} \right]$$

⇒ maximise  $\frac{1}{\sqrt{\pi N_0}} \exp \left\{ -\frac{(z - s_i)^2}{N_0} \right\} \cdot p(s_i)$  (take the log. and skip const. terms)

⇒ maximise  $-(z - s_i)^2 / N_0 + \log p(s_i)$

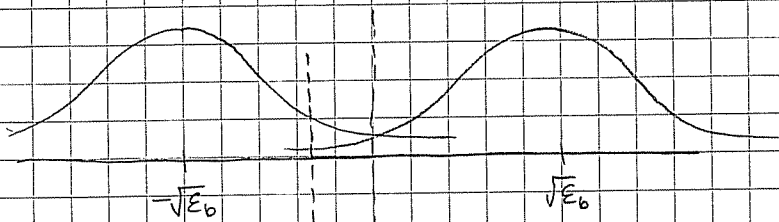
⇒ maximise  $-(z^2 + s_i^2 - 2zs_i) / N_0 + \log p(s_i)$  (but  $z^2$  and  $s_i^2$  is the same for  $i=1,2$ )

⇒ maximise  $2zs_i / N_0 + \log p(s_i)$

⇒ choose  $z \underset{s_2}{\overset{s_1}{>}} \frac{2z\sqrt{E_b}}{N_0} + \log p(s_1) \underset{s_2}{\overset{s_1}{>}} \frac{2z(-\sqrt{E_b})}{N_0} + \log p(s_2)$

⇒ choose  $z \underset{s_2}{\overset{s_1}{>}} \underbrace{\frac{N_0}{4\sqrt{E_b}} \log \frac{p(s_2)}{p(s_1)}}_{\gamma_0}$

2. What about  $P_B$ ?



$$\gamma_0 = \frac{N_0}{4\sqrt{E_b}} \log \frac{p(s_2)}{p(s_1)}$$

$$P_B = p(s_1) \int_{-\infty}^{\gamma_0} \frac{1}{\sqrt{\pi N_0}} e^{-\frac{(z-\sqrt{E_b})^2}{N_0}} dz + p(s_2) \int_{\gamma_0}^{\infty} \frac{1}{\sqrt{\pi N_0}} e^{-\frac{(z+\sqrt{E_b})^2}{N_0}} dz$$

We need to integrate gaussian pdf:s with tricky limits.

This is where the Q function comes in handy:

$$\int_x^{\infty} \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(t-m)^2}{2\sigma^2}} dt = \left[ \begin{array}{l} u = \frac{t-m}{\sigma} \Rightarrow t = \sigma u + m \\ dt = \sigma du. \text{ Limits: } \frac{x-m}{\sigma} \text{ and } \infty \end{array} \right]$$

$$= \frac{1}{\sqrt{2\pi}} \int_{\frac{x-m}{\sigma}}^{\infty} e^{-u^2/2} du = Q\left(\frac{x-m}{\sigma}\right)$$

Now we can calculate  $P_B$ . Note that  $\int_{-\infty}^{\gamma_0} \frac{1}{\sqrt{\pi N_0}} e^{-\frac{(z-\sqrt{E_b})^2}{N_0}} dz = \int_{-\gamma_0}^{\infty} \frac{1}{\sqrt{\pi N_0}} e^{-\frac{(z+\sqrt{E_b})^2}{N_0}} dz$

$$P_B = p(s_1) Q\left(\frac{-\gamma_0 + \sqrt{E_b}}{\sqrt{N_0}/2}\right) + p(s_2) Q\left(\frac{\gamma_0 + \sqrt{E_b}}{\sqrt{N_0}/2}\right)$$

3.

You have to decide for which value of  $E_b/N_0$  you want to plot the curve, but the shape is always the same: It is zero at the endpoints and peaks in the middle.

But if it peaks when  $p(s_1) = p(s_2) = 0.5$ , then why would we want them to be equiprobable.